

WHAT IS CLAIMED IS:

1. A distortion measurement method comprising:
  - a first formation step of repeating,  $m \times n$  times, shot exposure of arranging first marks on a photosensitive substrate via a reticle and a projection optical system in  $M$  rows and  $N$  columns at a predetermined column interval and a predetermined row interval, thereby forming first marks in  $M \times m$  rows and  $N \times n$  columns on the photosensitive substrate,  $M$  and  $m$  being natural numbers which are relatively prime,  $N$  and  $n$  being natural numbers which are relatively prime, and  $M > m$  and  $N > n$ ;
  - a second formation step of repeating,  $M \times N$  times, shot exposure of arranging second marks on the photosensitive substrate via the reticle in  $m$  rows and  $n$  columns at the predetermined column interval and the predetermined row interval, thereby forming second marks in  $M \times m$  rows and  $N \times n$  columns on the photosensitive substrate, the first and second marks formed in the first and second formation steps forming  $M \times m \times N \times n$  overlay marks;
  - a measurement step of measuring misalignment amounts of the first and second marks for each of the  $M \times m \times N \times n$  overlay marks; and
- 25 a calculation step of calculating a distortion amount of the projection optical system on the basis of the misalignment amounts measured in the measurement

step.

2. The method according to claim 1, wherein  
letting  $p_x$  be the predetermined column interval  
and  $p_y$  be the predetermined row interval,

5 in the first step, shot exposure is repeated at a  
shot interval of  $p_x \times N$  in a row direction and a shot  
interval of  $p_y \times M$  in a column direction, and  
in the second step, shot exposure is repeated at  
a shot interval of  $p_x \times n$  in the row direction and a  
10 shot interval of  $p_y \times m$  in the column direction.

3. The method according to claim 1, wherein in the  
calculation step, a distortion amount is calculated for  
a  $\xi$ th overlay mark formed from an  $i$ th first mark of a  
kth shot in the first formation step and a  $j$ th second  
15 mark of an  $l$ th shot in the second formation step by  
solving  $2 \times M \times m \times N \times n$  simultaneous equations  
obtained by substituting misalignment amount  
measurement values  $\delta_x(\xi)$  and  $\delta_y(\xi)$  in X and Y  
directions that are measured in the measurement step  
20 into

$$\delta_x(\xi) = dx_1(i) - dx_2(j) + ex_1(k) - ex_2(l) - \\ Y_1(i) \theta_1(k) + Y_2(j) \theta_2(l)$$

$$\delta_y(\xi) = dy_1(i) - dy_2(j) + ey_1(k) - ey_2(l) + \\ X_1(i) \theta_1(k) - X_2(j) \theta_2(l)$$

25 where

$dx_1(i)$ ,  $dy_1(i)$ : misalignment amounts of the  $i$ th first  
mark

$dx_2(j)$ ,  $dy_2(j)$ : misalignment amounts of the  $j$ th second mark

$ex_1(k)$ ,  $ey_1(k)$ ,  $\theta_1(k)$ : alignment errors of the  $k$ th shot in the first formation step

5    $ex_2(l)$ ,  $ey_2(l)$ ,  $\theta_2(l)$ : alignment errors of the  $l$ th shot in the second formation step

$X_1(i)$ ,  $Y_1(i)$ : coordinates of the  $i$ th first mark within the shot

$X_2(j)$ ,  $Y_2(j)$ : coordinates of the  $j$ th second mark within the shot.

10   4. The method according to claim 3, wherein when the simultaneous equations are solved in the calculation step, a respective sum of  $dx_2(j)$ ,  $dy_2(j)$ ,  $ex_1(k)$ ,  $ey_1(k)$ ,  $\theta_1(k)$ ,  $ex_2(l)$ ,  $ey_2(l)$ , and  $\theta_2(l)$  is assumed to be 0, and a respective sum of  $X_2(l) \times ex_2(l)$ ,  $Y_2(l) \times ey_2(l)$ ,  $Y_2(l) \times ex_2(l)$ , and  $X_2(l) \times ey_2(l)$  is assumed to be 0, for all the overlay marks.

20   5. The method according to claim 1, wherein the misalignment amount includes a misalignment amount between respective barycentric positions of the first and second marks which constitute the overlay mark.

25   6. A distortion measurement apparatus comprising: control means for controlling an exposure apparatus so as to form  $M \times m \times N \times n$  overlay marks on a photosensitive substrate by repeating,  $m \times n$  times, shot exposure of arranging first marks on the photosensitive substrate via a reticle and a projection

optical system in  $M$  rows and  $N$  columns at a predetermined column interval and a predetermined row interval to form first marks in  $M \times m$  rows and  $N \times n$  columns on the photosensitive substrate, and by

5 repeating,  $M \times N$  times, shot exposure of arranging second marks on the photosensitive substrate via the reticle in  $m$  rows and  $n$  columns at the predetermined column interval and the predetermined row interval to form second marks in  $M \times m$  rows and  $N \times n$  columns on

10 the photosensitive substrate,  $M$  and  $m$  being natural numbers which are relatively prime,  $N$  and  $n$  being natural numbers which are relatively prime, and  $M > m$  and  $N > n$ ;

measurement means for measuring misalignment amounts of the first and second marks for each of the  $M \times m \times N \times n$  overlay marks; and

calculation means for calculating a distortion amount of the projection optical system on the basis of the misalignment amounts of the first and second marks

20 which are measured for each of the  $M \times m \times N \times n$  overlay marks.

7. The apparatus according to claim 6, wherein

letting  $p_x$  be the predetermined column interval and  $p_y$  be the predetermined row interval,

25 said control means repeats shot exposure at a shot interval of  $p_x \times N$  in a row direction and a shot interval of  $p_y \times M$  in a column direction to form the

first marks in the  $M \times m$  rows and the  $N \times n$  columns,  
and repeats shot exposure at a shot interval of  $p_x \times n$   
in the row direction and a shot interval of  $p_y \times m$  in  
the column direction to form the second marks in the  $M$   
5  $\times m$  rows and the  $N \times n$  columns.

8. The apparatus according to claim 6, wherein said  
calculation means calculates a distortion amount for a  
 $\xi$ th overlay mark formed from an  $i$ th first mark of a  
kth shot by said first formation means and a  $j$ th second  
10 mark of an  $l$ th shot by said second formation means by  
solving  $2 \times M \times m \times N \times n$  simultaneous equations  
obtained by substituting misalignment amount  
measurement values  $\delta_x(\xi)$  and  $\delta_y(\xi)$  in  $X$  and  $Y$   
directions that are measured by said measurement means  
15 into

$$\begin{aligned}\delta_x(\xi) &= dx_1(i) - dx_2(j) + ex_1(k) - ex_2(l) - \\ &\quad Y_1(i)\theta_1(k) + Y_2(j)\theta_2(l) \\ \delta_y(\xi) &= dy_1(i) - dy_2(j) + ey_1(k) - ey_2(l) + \\ &\quad X_1(i)\theta_1(k) - X_2(j)\theta_2(l)\end{aligned}$$

20 where

$dx_1(i)$ ,  $dy_1(i)$ : misalignment amounts of the  $i$ th first  
mark

$dx_2(j)$ ,  $dy_2(j)$ : misalignment amounts of the  $j$ th second  
mark

25  $ex_1(k)$ ,  $ey_1(k)$ ,  $\theta_1(k)$ : alignment errors of the  $k$ th shot  
by said first formation means

$ex_2(l)$ ,  $ey_2(l)$ ,  $\theta_2(l)$ : alignment errors of the  $l$ th shot

by said second formation means

$X_1(i)$ ,  $Y_1(i)$ : coordinates of the  $i$ th first mark within  
the shot

$X_2(j)$ ,  $Y_2(j)$ : coordinates of the  $j$ th second mark within  
5 the shot.

9. The apparatus according to claim 8, wherein when  
said calculation means solves the simultaneous  
equations, a respective sum of  $dx_2(j)$ ,  $dy_2(j)$ ,  $ex_1(k)$ ,  
ey<sub>1</sub>(k),  $\theta_1(k)$ ,  $ex_2(l)$ ,  $ey_2(l)$ , and  $\theta_2(l)$  is assumed to  
10 be 0, and a respective sum of  $X_2(l) \times ex_2(l)$ ,  $Y_2(l) \times$   
 $ey_2(l)$ ,  $Y_2(l) \times ex_2(l)$ , and  $X_2(l) \times ey_2(l)$  is assumed to  
be 0, for all the overlay marks.

10. The apparatus according to claim 6, wherein the  
misalignment amount includes a misalignment amount  
15 between respective barycentric positions of the first  
and second marks which constitute the overlay mark.

11. An exposure apparatus comprising:

exposure means for transferring an image on a  
reticle onto a wafer by exposure light; and

20 storage means for generating and storing a  
correction value for exposure processing on the basis  
of a distortion amount obtained by executing a  
distortion measurement method defined in claim 1,

wherein the correction value is reflected in  
25 exposure processing by said exposure means.

12. A device manufacturing method comprising steps  
of:

installing manufacturing apparatuses for various processes including an exposure apparatus defined in claim 11 in a semiconductor manufacturing factory; and manufacturing a semiconductor device by a 5 plurality of processes using the manufacturing apparatuses.

13. A method comprising:

a first exposure step of exposing each of first shot regions on a substrate to a plurality of first 10 marks aligned at a predetermined interval via a master and a projection optical system;

a second exposure step of exposing each of second shot regions on the substrate to a plurality of second marks aligned at the predetermined interval via the 15 master and the projection optical system, the first and second shot regions being so arranged as to make positions of a plurality of transferred first and second marks on the substrate correspond to each other, the plurality of transferred first and second marks 20 being formed due to said first and second exposure step respectively, and number of the transferred first marks in the first shot region being larger than number of the transferred second marks in the second shot region; and 25 a calculation step of calculating a distortion amount of the projection optical system based on a positional difference measured for the transferred

first and second marks which correspond to each other.

14. A storage medium storing a program which causes a computer to execute a method, the method comprising:

5 shot regions on a substrate to a plurality of first marks aligned at a predetermined interval via a master and a projection optical system;

10 a second exposure step of exposing each of second shot regions on the substrate to a plurality of second marks aligned at the predetermined interval via the master and the projection optical system, the first and second shot regions being so arranged as to make positions of a plurality of transferred first and second marks on the substrate correspond to each other,

15 the plurality of transferred first and second exposure step being formed due to said first and second exposure step respectively, and number of the transferred first marks in the first shot region being larger than number of the transferred second marks in the second shot region;

20 and

25 a calculation step of calculating a distortion amount of the projection optical system based on a positional difference measured for the transferred first and second marks which correspond to each other.

15. An exposure apparatus comprising:

an exposure unit which exposes a substrate to a master pattern via a projection optical system; and

a control unit which executes a method defined in  
claim 13 to obtain a distortion amount of the  
projection optical system, and controls an exposure  
process by said exposure unit based on the obtained  
5 distortion amount.

16. A device manufacturing method comprising:  
providing an exposure apparatus defined in claim  
15; and  
manufacturing a device using the exposure  
10 apparatus.